Shared memory parallel programming models Pthread and OpenMP by example

Houssam-Eddine Zahaf houssameddine.zahaf@univ-nantes.fr



shared-mem



1 Introduction to shared-memory parallel programming model

2 Parallel programming using OpenMP

3 Pthread as shared memory parallel programming model





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4 Exercices

Shared memory model : Multiple CPU - Single DRAM



- Global memory which can be accessed by all processors of a parallel computer.
- Data in the global memory can be read/write by any of the processors.



Shared memory : programming

Programmed thanks to a collection of threads

- A thread is the smallest schedulable unit within an operating system
- Can be created dynamically



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- Might share variables



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Threads communicate

- implicitly by reading and writing shared variables
- coordinate using synchronization mechanisms on shared variables





Programming platforms for shared memory hardware

- Several Thread Libraries/systems
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 - OpenMP standard for application level programming OpenMP (Open Multi-Processing) is an application programming interface (API) that supports multi-platform shared-memory multiprocessing programming in C, C++, and Fortran on many platforms, instruction-set architectures and operating systems.



Programming platforms for shared memory hardware

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 - **PTHREADS** is the POSIX Standard (Portable Operating System Interface)
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 - **TBB** Thread Building Blocks Intel is a C++ template library developed by Intel for parallel programming on multi-core processors. Using TBB, a computation is broken down into tasks that can run in parallel. The library manages and schedules threads to execute these tasks.
 - CILK: Cilk, Cilk++, Cilk Plus and OpenCilk are general-purpose programming languages designed for multithreaded parallel computing. They are based on the C and C++ programming languages.
 - Java threads Built on top of POSIX threads : threads in the java virtual machine





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- Three languages supported: C, C++, Fortran
- Portable :
 - Supported on multiple operating systems: UNIX, Linux, Windows, etc.
 - Supported by multiple compilers : gcc, Intel C/C++, etc





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- Sequential code is executed by the main process/thread
- Parallel code can be executed by one or multiple workers
- Synchronization primitives can be used to synchronize each fork-joint phase
- It allows to parallelize:
 - loops
 - Region
 - Functions
 - etc.



OpenMP parallelization instruction are provided through directives and clauses
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OpenMP routine

Functions and subroutines are part of a OpenMP library loaded at link time



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OpenMP routine

Functions and subroutines are part of a OpenMP library loaded at link time

Behavior

- pragma(s) might trigger fork-join section
- the master task spawns ("forks") children tasks and ensures that at their completion the master thread "gathers" to continue onward the execution.

Main pragma(s)

We can define a parallel region using

#pragma omp parallel

/* Parallel region code */

We can define a parallel loop using

#pragma omp for
 /* the for loop */

OpenMP : sharing clauses

shared (...): list of shared variables by all OpenMP tasks

private(...): list of variables that are visible only by their task

- the variable is not initialized within the parallel part of the code
- the variable get its initial value when leaving the parallel region
- firstprivate(...): Similar to the previous but data are initialized with their value before the parallel part of the code.
- default (none, private, shared) : denotes the default behavior for given
 variables set to shared

by default if the sharing is not specified, it is set to shared



Hello parallel region

```
#include <stdio.h>
#include <stdlib.h>
#include <stdlib.h>
#include <omp.h>

int main(int argc, char ** argv){
    # pragma omp parallel
    {
        int tid = omp_get_thread_num();
        printf (" Hello, I am parallel [%d] \n",tid);
    }
    return EXIT_SUCCESS ;
}
```

zahaf:•	•••	> co	ode\$./he	llo_parregion.out	ľ
Hello,		am	parallel	[7]	
Hello,		am	parallel	[5]	
Hello,		am	parallel	[2]	
Hello,		am	parallel	[4]	
Hello,		am	parallel	[6]	
Hello,		am	parallel	[3]	
Hello,		am	parallel	[0]	
Hello,	I	am	parallel	[1]	

gcc hello_parregion.c -o hello_parregion.out -Wall -fopenmp



Hello share clauses (1)

```
#include <stdio.h>
#include <stdlib.h>
#include <omp.h>
int main(int argc, char ** argv) {
 int i = 0;
# pragma omp parallel private(i)
    int tid = omp_get_thread_num();
    i*=2:
   printf (" ID [%d] : i : %d \n",tid,i);
 return EXIT_SUCCESS ;
```



Hello share clauses (1)

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#include <stdio.h>
#include <stdlib.h>
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int main(int argc, char ** argv) {
 int i = 0;
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    int tid = omp_get_thread_num();
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```



Hello share clauses (1)

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int main(int argc, char ** argv) {
 int i = 0:
# pragma omp parallel private(i)
    int tid = omp_get_thread_num();
    i*=2;
   printf (" ID [%d] : i : %d \n",tid,i);
 return EXIT_SUCCESS ;
```

zaha	af : 🖓	•••	> (00	<pre>ie\$./share_clauses1.out</pre>
ID	[3]				
ID	[0]				65396
ID	[4]				
ID	[5]				
ID	[1]				
ID	[2]				
ID	[7]				
ID	[6]		i		Ø



Hello share clauses (2) - Correction

```
#include <stdio.h>
#include <stdlib.h>
#include <omp.h>
int main(int argc, char ** argv) {
 int i = 2:
# pragma omp parallel firstprivate(i)
    int tid = omp_get_thread_num();
    i*=tid;
   printf (" ID [%d] : i : %d \n",tid,i);
 return EXIT_SUCCESS ;
```

zaha	f:++	12	> C	00	le\$./share_clauses2.out
ID	[4]					
ID	[5]				10	
ID	[2]					
ID	[6]				12	
ID	[1]					
ID	[0]					
ID	[3]					
ID	[7]		i		14	



Hello share clauses

```
#include <stdio h>
#include <stdlib.h>
#include <omp.h>
int main(int argc, char ** argv) {
 int i = 2;
# pragma omp parallel default(shared)
   int tid = omp_get_thread_num();
   i*=tid;
    int z = 1;
    z++;
   printf (" ID [%d] : i : %d : %d\n",tid,i, z);
 return EXIT_SUCCESS ;
```

zaha	af : +	• • •	> 0	:00	s ./share clauses3.out
ID	[6]				12 : 2
ID	[2]				
ID	[1]				
ID	[3]				
ID	[4]				
ID	[5]				10 : 2
ID	[7]				70 : 2
ID	[0]		i		0 :_2



Loops by example

```
#include <stdio.h>
#include <stdlib.h>
#include <omp.h>
int main(int argc, char ** argv) {
# pragma omp parallel
#pragma omp for
    for (int i=0;i<10;i++) {
      int tid = omp_get_thread_num();
      printf (" ID [%d] : i : %d \n",tid,i);
 return EXIT SUCCESS :
```

zaha	af:•	•••	> (00	le\$./loops1.out
ID	[5]					
ID	[4]					
ID	[6]				8	
ID	[7]					
ID	[3]					
ID	[0]					
ID	[0]				1	
ID	[1]				2	
ID	[1]					
ID	[2]		i		4	

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- There is an implicit barrier at the end of the loop.
 - remove it by adding the clause nowait on the same line: #pragma omp for nowait



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Specify iteration scheduling: schedule(ScheduleType, chunksize)

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[static] distributes the iteration chunks across threads in a round-robin

- default chunksize is computer to load balance different threads
- useful when iterations are regular


Loops : a particular attention

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Specify iteration scheduling : schedule(ScheduleType, chunksize)

- **[static]** distributes the iteration chunks across threads in a round-robin
 - default chunksize is computer to load balance different threads
 - useful when iterations are regular
- [dynamic] (work stealing) divides the iteration space to multiple chunks. When complete a chunk, it dequeues the next one.
 - By default, chunksize is 1.
 - Very useful if the time to process individual iterations varies.

NANTE

Loops scheduling (Link configuration, result)

```
# include <stdio.h>
# include <stdlib.h>
# include <omp.h>
int main(int argc, char ** argv){
 int nthreads=0:
#pragma omp parallel
    nthreads= omp get num threads();
 int nb[nthreads];
 for (int i=0;i<nthreads;i++) nb[i]=0;</pre>
#pragma omp parallel for schedule(static, 3)
 for (int i=0;i<30;i++) {</pre>
    int tid = omp get thread num();
   nb[tid]++:
    printf("-> [%d] : %d \n", tid, i);
 for (int i=0;i<nthreads;i++)</pre>
    printf("[%d]=%d\n", i, nb[i]);
  return EXIT_SUCCESS ;
```



Loops scheduling (Link configuration, result)

	dynamic, 5	dynamic, 3	dynamic, 1	static, 5	static, 2
<pre># include <stdio.h></stdio.h></pre>					
<pre># include <stdlib.h></stdlib.h></pre>					
<pre># include <omp.h></omp.h></pre>	(-)	S 161 + 1		-> 101 : 12	S 161 + 5
<pre>int main(int argc, char ** argv){ int nthreads=0;</pre>	-> [2] : 10 -> [2] : 11 -> [2] : 12 -> [2] : 13	-> [6] : 1 -> [6] : 8 -> [6] : 9 -> [6] : 10	-> [0] : 0 -> [0] : 1 -> [0] : 2	-> [6] : 18 -> [6] : 19 -> [6] : 0	> [6] : 6 > [6] : 7 > [6] : 8
1	-> [2] : 14	-> [1] : 3	-> [0] : 24	-> [5] : 6 -> [7] : 21	·> [6] : 9 ·> [3] : 0
#pragma omp parallel	-> [5] : 25	-> [1] : 12 -> [1] : 13	-> [0] : 25 -> [0] : 26	-> [3] : 3	> [3] : 1
{	-> [5] : 26 -> [5] : 27	-> [1] : 14	-> [6] : 18	-> [6] : 20	·> [3] : 2 ·> [0] : 10
<pre>nthreads= omp_get_num_threads();</pre>	-> [5] : 28	-> [1] : 15	-> [2] : 6	-> [6] : 24	> [0] : 11
}	-> [5] : 29	-> [1] : 17	-> [3] : 9	-> [6] : 26	·> [0] : 12 ·> [0] : 13
<pre>int nb[nthreads];</pre>	-> [0] : 1	-> [1] : 18	-> [7] : 21	-> [6] : 27 -> [6] : 28	> [0] : 14
<pre>for (int i=0;i<nthreads;i++) nb[i]="0;</pre"></nthreads;i++)></pre>	-> [0] : 2	-> [1] : 19 -> [1] : 20	-> [1] : 3	-> [6] : 29	·> [5] : 20 ·> [5] : 21
<pre>#pragma omp parallel for schedule(static, 3)</pre>	-> [0] : 3	-> [1] : 21	-> [1] : 4	-> [4] : 1 -> [4] : 2	> [5] : 22
<pre>for (int i=0;i<30;i++) {</pre>	-> [1] : 5	-> [1] : 22	-> [1] : 3	-> [5] : 7	·> [5] : 23 ·> [5] : 24
<pre>int tid = omp_get_thread_num();</pre>	-> [1] : 6	-> [1] : 24	-> [1] : 28	-> [5] : 8 -> [2] : 15	> [4] : 25
nb[tid]++;	-> [1] : 7	-> [1] : 25	-> [1] : 29	-> [2] : 16	> [4] : 26 > [4] : 27
printf("-> [%d] : %d \n", tid, i);	-> [1] : 9	-> [1] : 20	-> [4] : 12	-> [2] : 17 -> [7] : 22	> [4] : 28
}	-> [3] : 15	-> [1] : 28	-> [4] : 14	-> [7] : 23	·> [4] : 29 ·> [3] : 3
<pre>for (int i=0;i<nthreads;i++)< pre=""></nthreads;i++)<></pre>	-> [3] : 16 -> [3] : 17	-> [1] : 29	-> [3] : 11	-> [1] : 10 -> [1] : 11	> [3] : 4
printf("[%d]=%d\n", i, nb[i]);	-> [3] : 18	-> [3] : 4	-> [6] : 19	-> [0] : 13	> [2] : 15 > [2] : 16
return EXIT_SUCCESS ;	-> [3] : 19	-> [0] : 6	-> [5] : 15	-> [3] : 4	> [2] : 17
}	-> [4] : 20	-> [4] : 5 -> [2] : 7	-> [5] : 16	-> [3] : 5	·> [2] : 18 ·> [2] : 19
,	-> [4] : 22	-> [6] : 11	-> [5] : 17	[0]=3	[0]=5
	-> [4] : 23	-> [5] : 0 [0]=1	-> [7] : 22	[2]=3	2]=5
	[0]=5	[1]=19	-> [2] : 7	[4]=3	3]=5
	[1]=5	[2]=1	-> [2] : 8	[5]=3	14 J=5
	[2]=5	[3]=1 [4]=1	[0]=6	[7]=3	[6]=5

[2]=3

What does it do?

```
# include <stdio.h>
# include <stdib.h>
# include <stdlib.h>
# include <omp.h>
int main(int argc, char ** argv){
    int count=0;
#pragma omp parallel for schedule(dynamic) shared(count)
    for (int i=0;i<30;i++){
        count+;
    }
    printf("-> %d \n", count);
    return EXIT_SUCCESS ;
}
```



What does it do?

```
# include <stdio.h>
# include <stdio.h>
# include <stdib.h>
# include <cmp.h>
int main(int argc, char ** argv){
    int count=0;
#pragma omp parallel for schedule(dynamic) shared(count)
    for (int i=0;i<30;i++){
        count++;
    }
    printf("-> %d \n", count);
    return EXIT_SUCCESS;
}
```

gcc critical_without.c -o critical_withou zahaf:···> code\$./critical_without.out -> 12 zahaf:···> code\$./critical_without.out -> 10 zahaf:···> code\$./critical_without.out -> 13



Critical section

```
# include <stdio.h>
# include <stdib.h>
# include <stdlib.h>
# include <omp.h>
int main(int argc, char ** argv){
    int count=0;
#pragma omp parallel for schedule(dynamic) shared(count)
for (int i=0;i<30;i++){
    # pragma omp critical
    {
        count++;
        }
    }
    printf("-> %d \n", count);
    return EXIT_SUCCESS;
}
```

zahaf:···> code\$./critical_with.out
-> 30



Critical section

```
zahaf:···> code$ ./critical_with.out
-> 30
```

pragma omp atomic can be used for an atomic arithmetic instruction
 if supported by hardware, low level atomic instruction execution can be generated



barrier Directive: #pragma omp barrier

- All threads will wait at this point
- All parallel regions have an implicit barrier.



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single **Directive**

- a single thread will execute the sequence of instructions located in the single region
- There is an implicit barrier at the end of the region



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- a single thread will execute the sequence of instructions located in the single region
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master Directive

- only the master will execute the sequence of instructions located in the single region,
- the region will be executed only once without implicit barrier at the end of the region.



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nowait Clause

can be used on omp for, single, and critical directives to remove the implicit barrier they feature



Environment variables

Under Linux: export VAR=VALUE

Variable Name	Default	Description
OMP_NUM_THREADS	Number of procs (OS)	Sets the maximum number of threads to use by parallel regions
OMP_SCHEDULE	STATIC	Sets the run-time schedule type and an optional chunk size
OMP_DYNAMIC	FALSE	Enables (.TRUE.) or disables (.FALSE.) the dynamic
		adjustment of the number of threads.
OMP_NESTED	FALSE	Enables (.TRUE.) or disables (.FALSE.)nested parallelism.
OMP_STACKSIZE	depend on arch.	Sets the number of bytes to allocate for each OpenMP
		thread to use as the private stack for the thread.
OMP_MAX_ACTIVE_LEVELS	No enforced limit	Limits the number of simultaneously executing threads .
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Other dependant variables (Intel)

- KMP_BLOCKTIME, (default 200 milliseconds) : Sets the time, in milliseconds, that a thread should wait, after completing the execution of a parallel region, before sleeping.
- KMP_LIBRARY, (default throughput) : Selects the OpenMP run-time library execution mode. The options for the variable value are throughput, turnaround, and serial.

...



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- All threads share a single executable, a single set of global variables,
- Each thread has its own stack (function arguments, private variables)
- Compared to OpenMP, it is a low-level API, indeed OpenMP is implemented on the top of Pthreads

Pthread execution model

main routines

int pthread_create(

```
pthread_t *thread,
  const pthread_attr_t *attr,
  void *(*start_routine) (void *),
  void *arg);

int pthread_join(pthread_t thread, void **retval);
```

void pthread_exit(void *retval);

int pthread_detach(pthread_t thread);



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Minimal Example using pthread

```
#include <stdio.h>
#include <stdlib h>
#include <unistd.h>
#include <pthread.h>
void *foo(void *arg) {
  sleep(1);
  printf("Hello, I am a thread \n");
  return NULL;
int main() {
  pthread t thread id;
  printf("Before invoking the thread function\n");
  pthread_create(&thread_id, NULL, foo, NULL);
  pthread_join(thread_id, NULL);
  printf("After Thread\n");
```



Specified through pthread_attr_t



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#include <pthread.h>

. . .

int pthread_attr_setschedpolicy(pthread_attr_t *att, int policy);



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...
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att : Scheduling attributes (the priority)



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Specified through pthread_attr_t

#include <pthread.h>

...
int pthread_attr_setschedpolicy(pthread_attr_t *att, int policy);

- att : Scheduling attributes (the priority)
- policy : Scheduling policy : SCHED_FIFO, SCHED_RR, SCHED_DEAD
- It is required to be super-user to apply the real-time scheduling policies
 → Attention : A thread with the highest RT priority will never be preempted.



Steps before creating pthreads

- Highest priority thread is scheduled first
- Priority is specified at thread creation time
 - \rightarrow pthread_attr_t et struct sched_param
- E1. create thread id structures and scheduling parameters :
 - pthread_t th; pthread_attr_t my_attr; struct sched_param param;
- E2. pthread_attr_init(&my_attr) \rightarrow initialization of the attribute
- E3. pthread_attr_setschedpolicy(&my_attr, SCHED_FIFO); \rightarrow select the scheduler
- E4. param.sched_priority = 1; \rightarrow Set the priority
- E5. pthread_attr_setschedparam(&my_attr, ¶m); \rightarrow Link scheduling parameters and attributes
- E6. pthread_create(&th1, &my_attr, foo, 0); \rightarrow launch the threads.
- E7. pthread_attr_destroy(&my_attr) ; \rightarrow destroying the parameters



Not based on the priority



Not based on the priority

Each task is served for a quantum



- Not based on the priority
- Each task is served for a quantum

Quantum is defined based on the thread execution, and the load of the system:

- Very small quantum: system overloading due to the important number of context switches
- Very long quantum: system reactivity is compromised
- Implemented through the management of two run-queues : served, and not-yet-served



- Not based on the priority
- Each task is served for a quantum

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Calling routine nice(), and setpriority() increases the quantum





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- BUT : in parallel programming, they share resources and communicate



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Constraints

- Guarantee that a task will have access to shared resources
- Ensure that the access to the shared resource is controlled
Solution : Mutex

The problem to solve

Consider thread A and B sharing a buffer. A produces the buffer and B consumes it. We would like to guarantee that if A is producing data, therefore B can not consume it, and vice-versa.

mutex m;

```
while(1) {
    // proccessing 3
    p(mutex);
    for (int i=0;i<buffer_size;i++) {
        buffer[i] = function(i);
        } // ressource partagée
        v(mutex);
}</pre>
```

```
while(1) {
    // proccessing 1
    p(mutex);
    process(buffer)
    v(mutex);
    // processing 2
```

Tâche B



Tâche A

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Revised solution

Issues

The solution depends on the duration of function function () and function process

General rule : reduce at maximum the duration of critical section

```
while (1) {
  // proccessing 3
  for (int i=0;i<buffer_size;i++) { p(mutex_1);</pre>
    buffer_1[i] = function(i);
  } // ressource partagée
  p(mutex_1);
  swap(buffer_1, buffer);
  v(mutex 1);
```

```
while(1) {
```

```
// proccessing 1
```

```
swap(buffer,buffer_2);
v(mutex 1);
```

```
process (buffer_2)
```



Mutex with pthread





Semaphores

```
nt sem_init(sem_t *semaphore, int pshared, unsigned int valeur);
nt sem_wait(sem_t *semaphore);
nt sem_timedwait(sem_t *semaphore, const struct timespec *abs_timeout);
nt sem_post(sem_t *semaphore);
```



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```

Barrier

int pthread_barrier_destroy(pthread_barrier_t *barrier); int pthread_barrier_init(pthread_barrier_t *restrict barrier, const pthread_barrierattr_t *restrict attr, unsigned count);



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Spin-locks

Spin-locks : active wait : thread is kept in active state



Other useful pthreads functions

- pthread_detach(pthread_t thread); Detach a thread
- pthread_exit(address_t value);Terminate this thread, returning value to any thread that is waiting for it
- pthread_cancel(pthread_t thread);Cancel a thread
- pthread_kill(pthread_t thread, int sig);Send a signal to a thread (e.g., SIGINT, SIGKILL)
- pthread_self(() Returns the thread id of this thread
- pthread_equal(pthread_t id1, pthread_t id2)Tells you if two thread ids refer to the same thread. It returns 0 (false) or !0 (true).
- pthread_once_t inits and pthread_once_init(&inits);



Pthread affinity: by example

- int pthread_setaffinity_np(pthread_t thread, size_t cpusetsize, const cpu_set_t *cpuset);
 - first parameter is the pid, 0 = calling thread
 - second parameter is the size of your cpuset
 - third param is the cpuset in which your thread will be placed. Each bit represents a CPU.



Pthread affinity: by example

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 - first parameter is the pid, 0 = calling thread
 - second parameter is the size of your cpuset
 - third param is the cpuset in which your thread will be placed. Each bit represents a CPU.

```
cpu_set_t cpuset;
int cpu = 2;
CPU_ZERO(&cpuset);
CPU_SET( cpu , &cpuset);
sched_setaffinity(0, sizeof(cpuset), &cpuset);
```



Thread input data passing by example

- Manipulated data are passed using the last parameter of function pthread_create
 - int pthread_create(..., void *restrict arg);
 - If multiple parameters are to be passed → must be regrouped in a struct or defined as global



Thread input data passing by example

Manipulated data are passed using the last parameter of function pthread_create

int pthread_create(..., void *restrict arg);

If multiple parameters are to be passed → must be regrouped in a struct or defined as global

```
#include ...
                                                               #include ...
                                                               struct couple
int a:
                                                                 int a:
int b:
                                                                 int b:
                                                               }:
v8DEoid *foo(void *arg) {
                                                               void *foo(void *arg) {
 sleep(1):
 printf("Hello, I am a thread %d %d \n", a, b);
                                                                 sleep(1);
 return NULL;
                                                                 return NULL:
int main() {
 a=1;
                                                               int main(){
 b=2:
                                                                 pthread t thread id;
 pthread t thread id;
 printf("Before invoking the thread function\n");
 pthread create (&thread id, NULL, foo, NULL):
 pthread join(thread id, NULL);
 printf("After Thread\n");
```

```
struct couple * c = (struct couple *) (arg);
printf("Hello, I am a thread %d %d n", c->a, c->b);
struct couple c=\{a = 1, b=2\};
printf("Before invoking the thread function\n"):
pthread create(&thread id, NULL, foo, &c);
pthread join (thread id, NULL);
printf("After Thread\n");
```

Example of parallel computations : data parallelism

Array addition using Pthreads





1 Introduction to shared-memory parallel programming model

2 Parallel programming using OpenMP

3 Pthread as shared memory parallel programming model



Exercise Work-stealing with OpenMP

define a work stealing mechanism for Pthreads to compute array addition.



```
long num steps = 10000;
double step;
int main ()
  int i; double x, pi, sum = 0.0;
  step = 1.0/(double) num steps;
  for (i=0; i<num steps; i++) {
    x = (i+0.5) * step;
    sum = sum + 4.0/(1.0+x*x);
  }
  pi = step * sum;
  printf("%lf \n", pi);
```

Create a parallel version of the pi program using a parallel construct, without any use of synchronization mechanisms (without parallelizing loops with the help of open mp).
 Improve the previous solution using synchronization mechanisms
 use parallel loops with openMP, improve the solving time using the OpenMP schedules