# Formal Software Engineering

# The B Method for correct-by-construction software

#### J. Christian Attiogbé

November 2012





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#### Agenda

#### The B Method: an introduction

- Introduction: what it is?
  - A quick overview
  - Example of specification
    - Light Control in a Room
- How to develop using B
  - System Analysis
  - Structuration: Abstract Machines
  - Modeling Data
  - Modeling Data Operations
  - Refinements
  - Implementation

# **Examples of development**

- Exemples
  - GCD (PGCD), euclidian division,
  - Sorting
- Basic concepts of the method
  - Modeling the static part (data)
  - Modeling the dynamic part(operations)
  - Proof of consistency
  - Refinement
  - Proofs of refinement
- Case studies (with AtelierB, Rodin)

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Introduction to B

#### **B** Method

- (..1996) A Method to specify, design and build sequential software.
- (1998..) Event B ... distributed, concurrent systems.
- (...) still evolving, with more sophisticated tools (aka Rodin) ;-(







#### Examples of application in railways systems



Figure: Synchronisation of platform screen doors - Paris Metro

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# **Industrial Applications**

- Applications in Transportation Systems (Alsthom>Siemens) braking systems, platform screen doors(line 13, Paris metro),
- KVS, Calcutta Metro (India), Cairo
- INSEE (french population recensement)
- Meteor RATP: automatic pilote, generalization of platform screen doors
- SmartCards (Cartes à puce) : securisation, ...
- Peugeot
- etc
- Highly needed competencies in Industries.

#### A Context that imposes Formal Method

The standard EN51128 "Systèmes de signalisation, de télécommunication et de traitement" :

Cette norme traite en particulier des méthodes qu'il est necessaire d'utiliser pour fournir des logiciels répondant aux exigences d'intégrité de la sécurité appliquées au domaine du ferroviaire. L'intégrité d'un logiciel est répartie sur cinq niveaux SIL, allant de SIL 0 à SIL 4. Ces niveaux SIL sont définis par association, dans la gestion du risque, de la fréquence et de la conséquence d'un événement dangereux. Afin de définir précisément le niveau de SIL d'un logiciel, des techniques et des mesures sont définies dans cette norme. (cf. ClearSy)

SIL: Safety Integrity Level

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# The Standard EN 50128: Software Aspect of the Control

Standard NF EN 50128

**Titre:** Railway Applications, system of signaling, telecommunication and processing equipped with software for the control and the security of railway systems.

**Domain:** Exclusively applicable to software and to the interaction between software and physical devices;

5 levels of criticity:

Not critical: SILO,

No dead danger for humans: SIL1, SIL2,

Critical: SIL3, SIL4

**Applicable to:** the software application; the operating systems; the CASE<sup>1</sup> tools:

Depending on the projects and the contexts, we will need formal methods to build the dependable software or systems.

# Method in Software Engineering

#### Formal Method=

- Formal Specification or Modeling Langaguage
- Formal reasoning System

#### B Method=

- Specification Language
  - Logic, Set Theory: data language
  - Generalized Substitution Language: Operations's language
- Formal reasoning System
  - Theorem Prover

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# Formal Development

#### Formel Software Development=

- Systematic transformation of a mathematical model into an executable code.
  - = Transformation from the abstract to the concrete
  - Passing from mathematical structures to programming structures
  - = Refinement into code in a programming language.

#### **B:** Formal Method

- + refinement theory (of abstract machines)
- ⇒ formal development method

#### Correct Development (no overflow, for a trajectory)

```
MACHINE
    CtrlThreshold /* to control two naturals X and Y */
             /* 0 <= x <= threshold
             \land \forall y . 0 < y < threshY */
             threshX, threshY
CONSTANTS
PROPERTIES threshX : INT & threshX = 10 ...
VARIABLES
        xx, yy
INVARIANT
        xx : INT & 0 <= xx & xx <= threshX
        yy : INT & 0 < yy & yy < threshY
INITIALISATION
               xx := 0 || yy := 1
OPERATIONS
        computeY =
             yy := ... /* an expression */
END
```

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# Correct Development....

```
OPERATIONS (continued)
setXX(nx) = /* specification of an operation with PRE */
PRE
    nx : INT & nx >= 0 & nx <= threshX
THEN
    xx := nx
END;

rx <-- getXX = /* specification of an operation */
BEGIN
    rx := xx
END</pre>
```

#### The GCD Example

From the abstract machine to its refinement into executable code.

mathematical model -> programming model

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 $\land \forall$  other divisors dx d > dx  $\land \forall$  other divisors dy d > dy \*/

# Constructing the GCD: abstract machine

```
pgcd1 /* the GCD of two naturals */
    /* gcd(x,y) is d \mid x \mod d = 0 \land y \mod d = 0
```

#### **OPERATIONS**

MACHINE

```
rr <-- pgcd(xx,yy) = /* OUTPUT : rr ; INPUT xx, yy */</pre>
```

**END** 

#### Constructing the GCD: abstract machine

```
OPERATIONS
rr <-- pgcd(xx,yy) = /* spécification du pgcd */</pre>
PRE
    xx : INT & xx >= 1 & xx < MAXINT
& yy : INT & yy >= 1 & yy < MAXINT
THEN
    ANY dd WHERE
    dd: INT
    & (xx - (xx/dd)*dd) = 0 /* d is a divisor of x */
    & (yy - (yy/dd)*dd) = 0 /* d is a divisor of y */
        /* and the other common divisors are < d */
    & !dx.((dx : INT & dx < MAXINT)
        & (xx-(xx/dx)*dx) = 0 & (yy-(yy/dx)*dx)=0) => dx < dd)
    THEN rr := dd
    END
END
```

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### Constructing the GCD: refinement

#### Constructing the GCD: refinement

```
rr <-- pgcd (xx, yy) = /* the refined operation */
    BEGIN
        VAR cd, rx, ry, cr IN
            cd := 1
            ; WHILE ( cd < xx \& cd < yy) DO
                ; rx := xx - (xx/cd)*cd ; ry := yy - (yy/cd)*cd
                IF (rx = 0 \& ry = 0)
                THEN /* cd divises x and y, possible GCD */
                    cr := cd /* possible rr */
                END
                ; cd := cd + 1; /* searching a greater one */
            INVARIANT
                xx : INT & yy : INT & rx : INT & rx < MAXINT
                & ry : INT & ry < MAXINT & cd < MAXINT
                & xx = cr^*(xx/cr) + rx & yy = cr^*(y/cr) + ry
            VARIANT
                xx - cd
            END
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```

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**END** 

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#### B Method: Global Approach

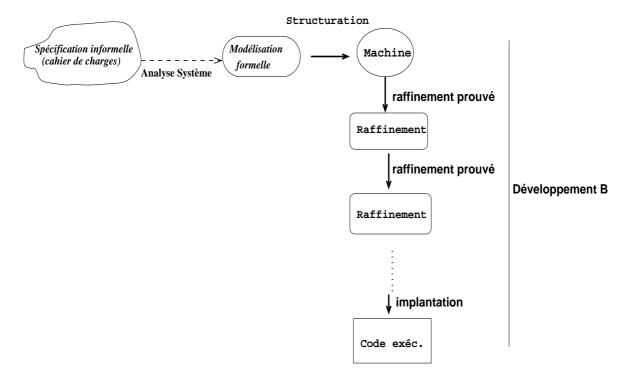


Figure: Analysis and B development

#### The B Method

#### Concepts and basic principles:

- abstract machine (state space + abstract operations),
- proved refinement (from abstract to concrete model)

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#### State and State Space

- Observe a variable in a logical model;
- It can take different values through the time, or several states through the time;
- For example a natural variable I: one can (logically) observe I=2, I=6, I=0,  $\cdots$  provided that I is modified;
- Following a modification, the state of I is changed;
- The change of states of a variable can be modeled by an action that substitutes a new value to the current one.
- More generally, for a natural *I*, there are possibly all the range or the naturals as the possible states for *I*: hence the state space.
- One generalises to several variables  $\langle I, J \rangle$ ,  $\langle V1, V2, V4, ... \rangle$

#### **Development Approach**

The approaches of Z, TLA, B, ... are said: model (or state) oriented

- Describe a state space
- Describe operations that explore the space
- Transition system between the states

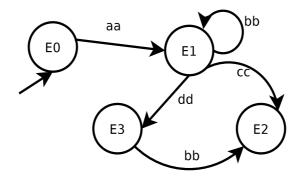


Figure: Evolution of a software system

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# **Specification Approach**

A tuple of variables describes a state

$$\langle mode = day, \ light = off, \ temp = 20 \rangle$$

A predicate (with the variables) describes a state space

$$light = off \land mode = day \land temp > 12$$

An operation that affects the variables changes the state

$$mode := day$$

Specification in B = model a transition system (with a logical approach)

#### **Abstract Machine**

variables

predicates

operation

```
MACHINE ...
SETS ...
VARIABLES
...
INVARIANT
... predicates
INITIALISATION
...
OPERATIONS
...
END
```

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#### **Abstract Machine**

```
MACHINE ReguLight
SETS

DMODE = {day, night}
; LIGHTSTATE = {off, on}
```

- An abstract machine has a name
- The SETS clause enables ones to introduce abstract or enumerated sets;
   These sets are used to type the variables
- The predefined sets are: NAT, INTEGER, BOOL, etc

#### **Abstract Machine**

#### **VARIABLES**

mode

- , light
- , temp

#### INVARIANT

mode : DMODE

& light : LIGHTSTATE

& temp : NAT

- The VARIABLES clause gathers the variables to be used in the specification
- The INVARIANT clause is used to give the predicate that describe the invariant properties of the abstract machine; its should be always true
- Both clauses go together.

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#### **Abstract Machine**

#### INITIALISATION

```
mode := day
|| temp := 20
|| light := off
```

An abstract machine should contain, an initial state of the specified system.
 This initial state should ensures the invariant properties.
 The INITIALISATION clause enebales one to initialise ALL the variables used in the machine The initialisation using substitutions, is done simultaneaously for all the variables.
 They can be modified later by the operations.

#### **Abstract Machine**

**OPERATIONS** 

```
changeMode =
CHOICE mode := day
OR mode := night
END
;
putOn =
light := on
;
putOff =
light := off
;
decreaseTemp = temp := temp - 1
```

increaseTemp = temp := temp +1

Within the clause OPERATIONS one provides the operations of the abstract machine.
 The operations model the change of state variables with logical substitutions (noted :=).
 The logical substitutions are generalised for more expressivity. The operations has a PREcondition (the POST is implicitely the invariant).

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**END** 

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#### Abstract Machine: example of Light Regulation

```
MACHINE ReguLight
SETS

DMODE = {day, night}
; LIGHTSTATE = {off, on}

VARIABLES

mode
, light
, temp
INVARIANT

mode : DMODE
& light : LIGHTSTATE
& temp : NAT

INITIALISATION

mode := day || temp := 20
|| light := off
```

```
OPERATIONS
changeMode =
CHOICE mode := day
OR mode := night
END
;
putOn =
light := on
;
putOff =
light := off
;
decreaseTemp = temp := temp - 1
;
increaseTemp = temp := temp +1
END
```

#### Abstract Machine: provides operations

An abstract machine provides operations which are callable from other external operations/programmes.

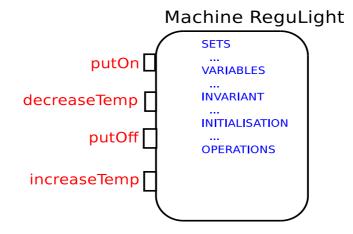


Figure: The operations are callable from outside

An operation of a machine cannot call another operation of the

Same machine

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### Interface of operations

(operations with or without input/output parameters)

No parameter:

nameOfOperation = ...

• Input parameters only:

nameOfOperation(p1, p2,  $\cdots$ ) = ...

Output parameters only:

• Input and Output parameters:

r1, r2, 
$$\cdots$$
 <--- nameOfOperation(p1, p2,  $\cdots$ ) = ...

#### **Light Regulation System**

#### Study

#### Requirements:

- The light should not be on during daylight.
- The temperature should not exceed 29 degrees during daylight.
- ...
- ⇒ Find and formalise the properties of the invariant.

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### Abstract Machine: example of the gauge

```
MACHINE MyGauge
VARIABLES
gauge
INVARIANT
gauge : NAT
& gauge >= 2
& gauge <= 45
INITIALISATION
gauge := 1 // !! what?
```

```
OPERATIONS
decrease1 =
PRE gauge > 2
THEN gauge := gauge - 1
END
; decrease(st) =
PRE st : NAT
& gauge - st >= 2
THEN
gauge := gauge - st
END
...
increase ...
END
```

#### Abstract Machine: example of ressources

```
MACHINE
                                     OPERATIONS
                                     addRsc(rr) = // adding
Resrc
SETS
                                     PRE
RESC
                                     rr : RESC & rr /: rsc &
CONSTANTS
                                     card(rsc) < maxRes</pre>
maxRes // a parameter
                                     THEN
                                     rsc := rsc \/ {rr}
PROPERTIES
maxRes : NAT & maxRes > 1
                                     END
VARIABLES
                                     rmvRsc(rr) = // removing
rsc
INVARIANT
                                     PRE
rsc <: RESC // a subset</pre>
                                     rr : RESC & rr : rsc
& card(rsc) <= maxRes //bound</pre>
INITIALISATION
                                     rsc := rsc - \{rr\}
rsc := {}
                                     END
                                     END
```

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# Basics of correct program construction

Consider operations on a bank account:

a withdrawal of givenAmount

```
begin
   account := account - givenAmount
end
```

a deposit on the account of newAmount

```
begin
   account := account + newAmount
end
```

\*\* these operations are not satisfactory, they don't take care of the constraints (the threshold to not overpass).

#### Basics of correct program construction

a withdrawal givenAmount

```
withdrawal(account, givenAmount)=
pre
  account - givenAmount >= 0 //unauthorised overdraft
begin
  account := account - givenAmount
end
```

Before calling the operation, we should ensure that it does not overpass the autorised amount.

```
IF withdrawalPossible(account, givenAmount)
    THEN withdrawal(account, givenAmount)
END
```

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### Basics of correct program construction (before B)

Consider two naturals natN and natD. What happens with the following statement?

```
res := natN / natD
```

What was expected:

```
IF (natD /= 0)
  THEN res := natN / natD
END
```

Indeed, the division operation has a precondition: (denom /= 0)

#### B: principle of the method

The control with an invariant of a system (or of a software)

- one models the space of correct states with a property (a conjunction of properties).
- While the system is in these states, it runs safely; it should be maintain within these states!
- We should avoid the system going out from the state space
- Hence, be sure to reach a correct state before performing an operation.

Examples: trajectory of a robot (avoid collision points before moving).

The operations that change the states has a precondition.

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### B: logical approach

Originality of B: every thing in logics (data and operations)

• state space: Invariant: Predicate : P(x,y,z)A state: a valuation of variables  $x := v_x$   $y := v_y$   $z := v_z$  in P(x,y,z) $\Rightarrow$  Logical substitution

• An operation: transforms a correct (state) into another one.

Transform a state = predicate transformer (invariant)

Operation = predicate transformer = substitution

other effects than affectation ⇒ generalized substitutions

#### B: the practice

#### A few specification rules in B

- An operation of a machine cannot call another operation of the same machine (violation of PRE);
- One cannot call in parallel from outside a machine two of its operation (for example : incr || decr);
- A machine should contain auxilliary operations to check the preconditions of the principal provided operations;
- The caller of an operation should check its precondition before the call ("One should not divide by 0");
- During refinement, PREconditions should be weaken until they desappear(Be careful, this is not the case with Event-B);
- ...

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#### B: the foundations

- First Order Logic
- Set Theory (+ types)
- Theory of generalized substitutions
- Theory of refinement
- and a good taste of: abstraction and composition!

#### **B: CASE Tools**

- Modularity:
   Abstract Machine, Refinement, Implementation
- Architecture of complex applications:
   with the clauses SEES, USES, INCLUDES, IMPORTS, ...
- CASE:Editors, analysers, provers, ...

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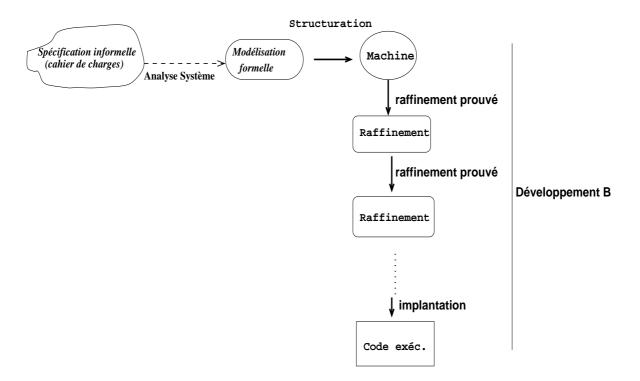
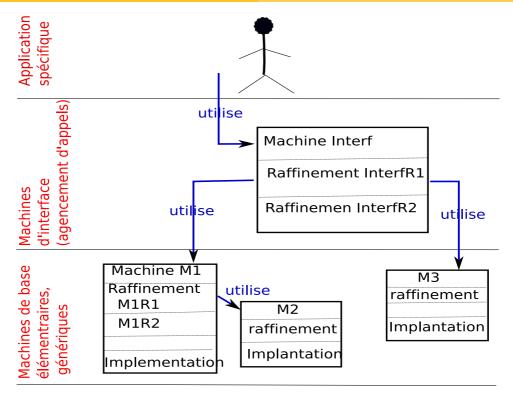


Figure: Analysis and B development



Bibliothèques de machines prédéfinies

Figure: Structure of a B Development

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#### Position - other methods

- B: Unique framework for (software lifecycle):
  - Analysis
  - Specification/Modeling
  - Design
  - Development
- B: Stepwise Refinements from abstract model to concrete one.
- ◆ (Other) Approaches: development, test à postériori → tests

#### Constructing the GCD: abstract machine

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Examples of specifications in B

#### Constructing the GCD: abstract machine

```
OPERATIONS
rr <-- pgcd(xx,yy) = /* spécification du pgcd */</pre>
PRE
    xx : INT & xx >= 1 & xx < MAXINT
& yy : INT & yy >= 1 & yy < MAXINT
THEN
    ANY dd WHERE
    dd: INT
    & (xx - (xx/dd)*dd) = 0 /* d is a divisor of x */
    & (yy - (yy/dd)*dd) = 0 /* d is a divisor of y */
        /* and the other common divisors are < d */
    & !dx.((dx : INT & dx < MAXINT)
        & (xx-(xx/dx)*dx) = 0 & (yy-(yy/dx)*dx)=0) => dx < dd)
    THEN rr := dd
    END
END
```

### Constructing the GCD: refinement

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Examples of specifications in B

#### Constructing the GCD: refinement

```
rr \leftarrow pgcd (xx, yy) = /* the refined operation */
    BEGIN
        VAR cd, rx, ry, cr IN
            cd := 1
            ; WHILE ( cd < xx \& cd < yy) DO
                ; rx := xx - (xx/cd)*cd ; ry := yy - (yy/cd)*cd
                IF (rx = 0 \& ry = 0)
                THEN /* cd divises x and y, possible GCD */
                     cr := cd /* possible rr */
                END
                ; cd := cd + 1 ; /* searching a greater one */
            INVARIANT
                xx : INT & yy : INT & rx : INT & rx < MAXINT
                & ry : INT & ry < MAXINT & cd < MAXINT
                & xx = cr*(xx/cr) + rx & yy = cr*(y/cr) + ry
            VARIANT
                xx - cd
            END
```

#### After the examples

... Let's dig a bit ...

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#### Examples of specifications in B

# A simplified general shape of an abstract machine

```
MACHINE
                            /* Name and parameters */
     M (prm)
CONSTRAINTS
                            /* Predicate on X and x */
/* clauses uses, sees, includes, extends, */
SETS
                             /* list of basic sets identifiers */
     ENS
CONSTANTS
                             /* list of constants identifiers */
     K
PROPERTIES
                             /* preedicate(s) on K */
VARIABLES
                             /* list of variables identifiers */
DEFINITIONS
                             /* list of definitions (macros) */
     D
```

#### A simplified shape of an abstract machine (cont'd)

```
INVARIANT

/* a predicate */

INITIALISATION U /* the initialisation */

OPERATIONS

u \leftarrow O(pp) = /* an operation O */

PRE
P

THEN
Subst
END;
...

end
```

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Examples of specifications in B

### Semantics: consistency of a machine

#### $\exists prm.C$

It is possible to have values f parameters that meet the constraints

$$C \Rightarrow \exists (ENS, K).B$$

There are sets and constants that meet the properties of the machine

$$B \wedge C \Rightarrow \exists V.I$$

There are a state that meets the invariant

$$B \wedge C \Rightarrow [U]I$$

The initialisation establishes the invariant

For each operation of the machine

$$B \wedge C \wedge I \wedge P \Rightarrow [Subst]I$$

Each operation called under its precondition preserves the invariant

### **Proof Obligations (PO)**

There are the predicates to be proven to ensure the consistency (and the correction) of the mathematical model defined by the abstract machine.

The designer of the machine has two types of proof obligations:

- prove that the INITIALISATION establishes the invariant;
- prove that each OPERATION, when called under its precondition, preserves the invariant.

$$I \wedge P \Rightarrow [Subst]I$$

In practice, one has tools assistance to discharge the proof obligations.

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Examples of specifications in B

# Semantics of a machine - Consistency

To formally establish the condition for the correct functionning of a machine, one uses proof obligations.

To guaranty the correction of a machine, we have two main proof obligations:

- The initialisation establishes the invariant
- Each operation of the machine, when called under its precondition, preserves the invariant.

These are logical expressions, predicates, which are proved.

# New Example

...SORTING...

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Examples of specifications in B

# Example of Specifying Sorting with B

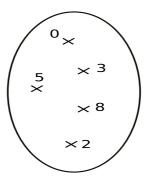


Figure: Modeling the Sorting of (a set of) Naturals

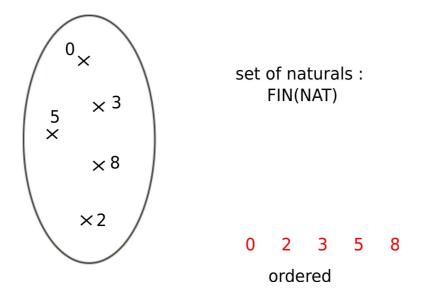


Figure: Modeling the Sorting: ordering the set of Naturals

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Examples of specifications in B

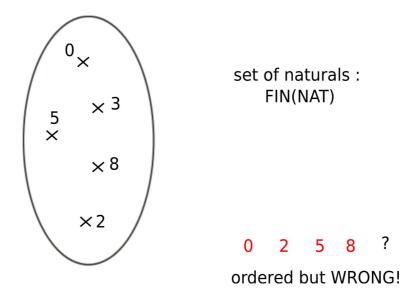


Figure: Modeling the Sorting: be careful!

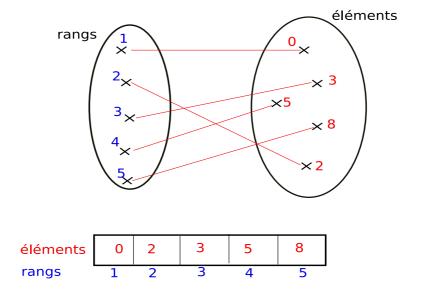


Figure: Modeling the Sorting

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Examples of specifications in B

```
MACHINE
   SpecSort
   /* specify an appli that gets naturals and then sort them */
SEES
         Sort /* To use the previous machine */
SETS
         SortMode = {insertion, extraction}
VARIABLES
         unsorted, sorted, mode
INVARIANT
          unsorted : FIN(NAT)
&
         sorted : seq(NAT)
         mode : SortMode
&
         ((mode = extraction) => (sorted= sortOf(unsorted)))
&
```

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Examples of specifications in B

```
/* MACHINE SpecTri
(continued ...) */
        input(xx) =
        PRE
               xx : NAT & mode = insertion
        THEN
               sorted :: seq(NAT)
        END
        moveToExtraction() =
        PRE
               mode = insertion
        THEN
               mode := extraction ||
               sorted := sortof(unsorted)
        END
                                                        990
```

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Examples of specifications in B

```
/* MACHINE SpecTri
(continued ...) */
yy <- extract(ii) =</pre>
         PRE
                  ii : dom(sorted) & mode = extraction
          THEN
                  yy := sorted(ii)
         END
END
```

#### B - Data Language - sets and typing

- Predefined Sets (work as types)
   BOOL, CHAR,
   INTEGER (Z), NAT (N), NAT1 (N\*),
   STRING
- Cartesian Product E x F
- The set of subsets (powerset) of E  $\mathcal{P}(E)$  written POW(E)

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Data Modeling Language

#### B - Data Language

#### With the data language

- we model the state space of a system with its data
- we describe the invariant properties of a system

#### Modeling the state:

- Abstraction, modeling (abstract sets, relations, functions, ...)
- Logical Properties, or algebraic properties.

#### B - Data Language

- When we model a system (with the set of its states) and make explicit its (right) properties, we ensure thereafter that the system only goes through the set of states that respect the defined properties: it is the consistency of the system.
- To show that it is possible to have states satisfying the given properties, one builds at least one state (it is the initial state).
- The specified system is correct if after each operation, the reached state is a state satisfying the given invariant properties.

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**Data Modeling Language** 

#### B - Data Language

#### First Order Logic

Description	Notation	Ascii
and	$p \wedge q$	p & q
or	$p \vee q$	p or q
not	$\neg p$	not p
implication	$p \Rightarrow q$	(p) ==> (q)
univ. quantif.	$\forall x.p(x)$	!x.(p(x))
exist. quantif.	$\exists x.p(x)$	#x.(p(x))

Variables should be typed:

```
\#x.(x : T ==> p(x)) \text{ and } !x.(x : T ==> p(x))
```

# B - Data Language

#### The standard set operators

E, F and T are sets, x an member of F

Description	Notation	Ascii
union	$E \cup F$	E \/ F
intersection	$E \cap F$	E /\ F
membership	$x \in F$	x:F
difference	$E \setminus F$	E - F
inclusion	$E \subseteq F$	E <: F
selection	choice(E)	choice(E)

- + generalised Union and intersection
- + quantified Union et intersection

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Data Modeling Language

# B - Data Language

In ascii notation, the negation is written with /.

Description	Notation	Ascii
not member	$x \notin F$	x /: F
non inclusion	$E \nsubseteq F$	E /<: F
non equality	$E \neq F$	E /= F

#### **Generalised Union**

an operator to achieve the generalised union of well-formed set expressions.

$$S \in \mathcal{P}(\mathcal{P}(T))$$
  
 $\Rightarrow$   
 $union(S) = \{x \mid x \in T \land \exists u.(u \in S \land x \in u)\}$   
**Example**

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Data Modeling Language

#### **Quantified Union**

an operator to achieve the quantified union of well-formed set expressions.

$$\forall x.(x \in S \Rightarrow E \subseteq T)$$

$$\Rightarrow$$

$$\bigcup x.(x \in S \mid E) = \{y \mid y \in T \land \exists x.(x \in S \land y \in E)\}$$

#### **Exemple**

$$UNION(x).(x \in \{1, 2, 3\} \mid \{y \mid y \in NAT \land y = x * x\})$$
$$= \{1\} \cup \{4\} \cup \{9\} = \{1, 4, 9\}$$

#### Generalised Intersection

an operator to achieve the generalised intersection of of well-formed set expressions.

$$S \in \mathcal{P}(\mathcal{P}(T))$$
  
 $\Rightarrow$   
 $inter(S) = \{x \mid x \in T \land \forall u.(u \in S \Rightarrow x \in u)\}$ 

#### **Example**

 $inter(\{\{aa, ee, ff, cc\}, \{bb, cc, gg\}, \{dd, ee, uu, cc\}\}) = \{cc\}$ 

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Data Modeling Language

#### **Quantified Intersection**

an operator to achieve the quantified intersection of well-formed set expressions.

$$\forall x.(x \in S \Rightarrow E \subseteq T)$$

$$\Rightarrow$$

$$\cap x.(x \in S \mid E)$$

$$= \{y \mid y \in T \land \forall x.(x \in S \Rightarrow y \in E)\}$$

#### **Example**

$$INTER(x).(x \in \{1, 2, 3, 4\} \mid \{y \mid y \in \{1, 2, 3, 4, 5\} \land y > x\})$$
  
=  $inter(\{\{1, 2, 3, 4, 5\}, \{2, 3, 4, 5\}, \{3, 4, 5\}, \{4, 5\}\})$ 

## Relations

Description	Notation	Ascii
relation	$r:S\leftrightarrow T$	r : S <-> T
domain	$dom(r) \subseteq S$	dom(r) <: S
range	$ran(r) \subseteq T$	ran(r) <: T
composition	r;s	r;s
composition r(s)	$r \circ s$	r(s)
identity	id(S)	id(S)

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#### Data Modeling Language

# Relations (continued)

Description	Notation	Ascii
domain restrictition	$S \triangleleft r$	S < r
range restriction	$r \triangleright T$	r  > T
domain antirestriction	$S \triangleleft r$	S <<  r
range antirestriction	$r \Rightarrow T$	r  >> T
inverse	$r^{\sim}$	r ~
relationnelle image	r[S]	r[S]
overiding	<i>r</i> 1 ⊕ <i>r</i> 2	r1 <+ r2
direct product of rel.	$r1 \otimes r2$	r1 >< r2
closure	closure(r)	closure(r)
reflexive trans. closure	closure1(r)	closure1(r)

## **Functions**

Description	Notation	Ascii
partial function	$S \rightarrow T$	S +-> T
total function	$S \to T$	S> T
partial injection	$S \rightarrowtail T$	S >+-> T
total injection	$S \rightarrowtail T$	S >> T
partial surjection	S  woheadrightarrow T	S +->> T
total surjection	$S \longrightarrow T$	S>> T
total bijection	$S \rightarrowtail T$	S >->> T
lambda abstraction	$\%x.(P \mid E)$	

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#### Data Modeling Language

# Sequences

Description	Notation
sequence of elements of T	seq(T)
	$= union(n).(n \in N)$
	$ 1n \rightarrow T)$
empty sequence	
injective sequence of element of T $T$	iseq(T)
bijective sequence of element of T $T$	perm(T)
size of a sequence $s$	size(s) = card(dom(s))

# Sequences (continued)

Description	Notation
first element of a seq. s	first(s) = s(1)
last element of a seq. $s$	first(s) = s(1)  last(s) = s(size(s))
restrict. of $s$ t its s $n$ first elem.	
elments	s <b>†</b> n
elimination of the first $n$	
elements of s	$s\downarrow n$

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Basic Concepts of the Dynamic Part

# **Modeling Operations**

Basic Concepts of the Dynamic Part

#### Weakest preconditions

**Context:** Hoare/Floyd/Dijkstra Logic Hoare triple (State, state space, statements, execution, Hoare triple)

S a statement and R a predicate that denotes the result of S. wp(S,R), is the predicate that descrives: the set of all states | the execution of S beginning with one of them **terminates** in a *finite time* din a state satisfaying R, wp(S,R) is the *weakest precondition* of S with respect to R.

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Basic Concepts of the Dynamic Part

#### Some examples

Let S be an assignment and

*R* the predicate  $i \le 1$ 

$$wp(i := i + 1, i \le 1) = (i \le 0)$$

Let *S* be the conditional:

if  $x \ge y$  then z := x else z := yand R the predicate z = max(x, y)

$$wp(S, \mathbb{R}) = Vrai$$

#### Weakest preconditions - meaning

The meaning of wp(S,R) can be make precise with two properties:

 wp(S, R) is a precondition guarantying R after the execution of S, that is:

$$\{wp(S,R)\}\ S\ \{R\}$$

• wp(S,R) is the weakest of such preconditions, that is: if  $\{P\}$  S  $\{R\}$  then  $P \Rightarrow wp(S,R)$ 

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Basic Concepts of the Dynamic Part

#### Weakest preconditions - meaning

In practice a program S establishes a postcondition R.

Hence the interest for the precondition that permits to establish R. wp is a function with two parameters:

a statement (or a program) S and

a predicate R.

For a fixed S, we can view wp(S, R) as a function with only one parameter  $wp_S(R)$ .

The function  $wp_S$  is called *predicate transformer* - Dijkstra It is the function which associates to every predicate R the weakest precondition such that  $\{P\}$  S  $\{R\}$ .

#### B: Generalized Substitutions - Axioms

Generalisation of the classical substitution of the Logic (to model the behaviours of operations).

Consider a predicate R to be established, the semantics of generalized substitution is defined by the predicate transformer.

- Simple Substitution SSemantics [S]R is read : S establishes R
- Multiple Substitution x, y := E, FSemantics [x, y := E, F]R

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Basic Concepts of the Dynamic Part

# B: generalized substitutions - Basic set of GS

The abstract syntax language to specify the operations:

Le *R* be the invariant, *S*, *T* substitutions

Name	Abs. Synt.	definition	equivalent in logic
neutral (id.)	skip	[skip]R	R
Pre-condition	$P \mid S$	$[P \mid S]R$	$P \wedge [S]R$
Bounded choice	$S \parallel T$	[S [] T]R	$[S]R \wedge [T]R$
Guard	$P \implies T$	$[P \implies T]R$	$P \Rightarrow [T]R$
Unbounded	@x.S	[@x.S]R	$\forall x.[S]R$
			x bounded (not free) in R

enough as B specification language but ...

#### Non determinism - Substitutions

- Abstraction ⇒ (possible)non determinism. OK for specifying.
- Concretisation ⇒ refinement into code
- Extending the basic GSL set to other substitutions closed to programming

```
CASE OF
SELECT
IF THEN ELSE
```

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Basic Concepts of the Dynamic Part

# B - Generalized substitutions language

Syntactic extension of substitutions: basic substitution set

#### **Basis Substitution**

```
noted S

Syntactic Extension

BEGIN

S

END
```

#### Simultaneous Substitutions

Consider *S* and *T* two substitutions.

```
S being x := E and 
T being y := F
note S | | T
```

# B - generalized substitution Language

#### **Neutral Substitution**

Syntactic extension

skip

skip

Subst. with precondition

Syntactic extension

 $P \mid S$ 

**PRE** 

P

**THEN** 

S

**END** 

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Basic Concepts of the Dynamic Part

# B - generalized substitution Language

#### **Bounded choice**

Syntactic extension

 $S \parallel T$ 

CHOICE

S OR

Т

END

#### **Guarded Substitution**

Syntactic extension

$$(P \Longrightarrow T) \ \ \ \ (\neg P \Longrightarrow S)$$

IF P

THEN T

ELSE S

**END** 

## B - generalized substitution Language

#### Unbounded Choice Substitution Syntactic extension

$$@x.S_x$$

VAR x IN Sx

**END** 

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Basic Concepts of the Dynamic Part

# Extending the basic substution set: non-deterministic

#### Nondeterministic @

$$@x.(P_x \implies S_x)$$

#### Syntactic extension

ANY x WHERE Px THEN Sx END

#### Extending the basic substution set: non-deterministic

#### Nondeterministic $x :\in U$

(becomes member)

$$@y.(y \in U \implies x := y)$$

#### Syntactic extension

THEN 
$$x := y$$

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Basic Concepts of the Dynamic Part

## B - generalized substitution Language

Extensions... non-deterministic

Nondeterministic x : P(x)

(x such that P)

x: P(x)

#### **Proof Obligations**

...Proof Obligation (PO)...

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**Proof Obligations** 

#### **Consistency Proof Obligations**

```
MACHINE ThreshCtrl
              thresX, threshY
CONSTANTS
                thresX : INT & thresX = 10 ...
PROPERTIES
VARIABLES
               \mathbf{X}\mathbf{X}
INVARIANT
                 xx : INT & 0 <= xx & xx <= thresX
                    xx := 0
INITIALISATION
OPERATIONS
setXX(nx) = /* an operation with PRE */
PRE
       nx : INT & nx >= 0 & nx <= thresX
THEN
    xx := nx
END
; incrXX(px) = /* incrementation of xx with px */
PRE
        px : INT & xx+px >= 0 & xx+px <= thresX
THEN
    xx := xx+px
END
END
```

#### **Proof Obligations (recall)**

The predicates to be proved to ensure the consistency (and the correction) of the mathematical model defined by the abstract machine. The machine developer has two kinds of PO:

- to prouve that the INITIALISATION establishes the invarant: [Init]I
- to prove that each OPERATION, when it is called under its precondition, preserves the invariant.

$$I \wedge P \Rightarrow [Subst]I$$

In practice, CASE tools are used to help in discharging the proofs.

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**Proof Obligations** 

# Proof of the operation setXX(nx)

We must prove that  $I \wedge P \Rightarrow [Subst]I$ 

```
INVARIANT xx: INT & 0 <= xx & xx <= thresX

setXX(nx) =
PRE
   nx: INT & nx >= 0 & nx <= thresX

THEN
   xx := nx  /* Subst */
END

INVARIANT xx: INT & 0 <= xx & xx <= thresX
```

(use white/blackboard)

# Precondition computation / preservation of the invariant

```
xx : INT & 0 <= xx & xx <= thresX

setXX(nx) =
PRE
... ?
THEN
xx := nx /* Subst */
END

nx : INT & 0 <= nx & nx <= thresX
```

We express [Subst]I and obtain a predicate which should be true!

 $nx : INT \& 0 \le nx \& nx \le thresX$ ?

It is the precondition!

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**Proof Obligations** 

# Precondition computation / preservation of the invariant

We express [Subst]I and obtain a predicate which should be true!

 $xx+px : INT \& 0 \le xx+px \& xx+px \le thresX$ ?

hence the precondition: px : INT & 0 <= xx+px & xx+px <= thresX

#### Example of ressources allocation (recall)

```
MACHINE
                                   OPERATIONS
                                   addRsc(rr) = // adding
Resrc
SETS
                                   ressources
RESC
                                   PRE
                                   rr : RESC & rr /: rsc &
CONSTANTS
maxRes // a parameter
                                   card(rsc) < maxRes</pre>
PROPERTIES
                                   THEN
                                   rsc := rsc \/ {rr}
maxRes : NAT & maxRes > 1
VARIABLES
                                   END
rsc
                                   rmvRsc(rr) = //
INVARIANT
rsc <: RESC // subset
                                   allocation
& card(rsc) <= maxRes //</pre>
                                   PRE
bounded
                                   rr : RESC & rr : rsc
INITIALISATION
                                   THEN
rsc := {}
                                   rsc := rsc - \{rr\}
                                   END
                                            990
```

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**Proof Obligations** 

## Consistency of a machine: proof obligation

```
The Initialisation establishes the invariant: [U]I; [rsc := {}] (rsc <: RESC & card(rsc) <= maxRes) ? Replace variables with their values: {} <: RESC & card({}) <= maxRes ? Reduce {} <: RESC & 0 <= maxRes ?
```

TRUE

#### Consistency of a machine: proof obligation

Preservation of the invariant by: addRsc(rr)

```
rsc <: RESC & card(rsc) <= maxRes

PRE
    rr : RESC & rr /: rsc & card(rsc) < maxRes

THEN
    rsc := rsc \/ {rr}

END

rsc <: RESC & card(rsc) <= maxRes
```

Replace variables with their values in I:

rsc \/ {rr} <: RESC & card(rsc \/ {rr}) <= maxRes ?

(use white/blackboard)

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**Case Studies** 

#### **Case Studies**

...Cas Euclide...

#### Démo division euclidienne

```
Euclid Pgm demo
           Menu de l'application
        +----+
            Nouvelle division
            Quitter
         choix ? 1
 Division euclidienne
 Donnez le dividende (entre 3 et 78)
 Donnez le diviseur (entre 1 et 78)
78
 Resultat de la division : 0
 Reste de la division : 56
                                       ₹ 200
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```

#### **Case Studies**

#### suite démo

```
+-----+

+ Menu de l'application +

+------+

Nouvelle division : 1

+------+

Quitter : 0

+-----+

choix ? 1

Division euclidienne

Donnez le dividende (entre 3 et 78)

67

Donnez le diviseur (entre 1 et 78)

6

Resultat de la division : 11

Reste de la division : 1
```

## Spécification de Euclide

```
MACHINE
       euclide
OPERATIONS
reste, quot ← calculReste (divis, divid) =
PRE
        divis \in NAT \land divid \in NAT \land divis > 0
       divis ≤ divid /* sinon B le trouve */
THEN
       ANY vq, vr WHERE
              vq \in NAT
              vr \in NAT
              divid = vq*divis + vr
       THEN
              quot := vq
              reste := vr
       END
END
END
```

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Case Studies

# Example of development with B

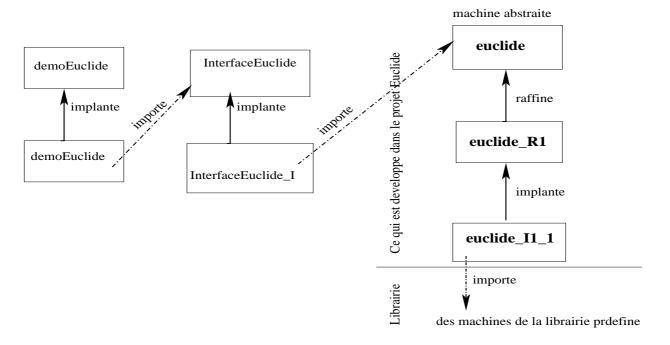


Figure: Architecture of applications with B

#### Refinement: development technique

#### Idea of refinement:

- We start with an abstract machine defining an abstract mathematical model,
- we refine this model to obtain a concrete model :
  - the abstract model is not executable.
     Why? (it is defined with mathematical objects)
  - to obtain an equivalent model,wrt to functionalities, but more concrete.

(it is described with programming objects)

There is a well-defined Theory of refinement [Morgan 1990; R-J. Back 1980; C. Ralph-Johan Back, Joakim Wright, 1998]

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Refinement

#### Refinement: development technique

- The objective of refinement is the construction of executable code.
- We should guaranty that the refinement is correct: (refinement proof).
- ⇒ refinement proof obligations

#### Approach of refinement

#### What to refine in the model?

The variables and the invariant
 Static Part - state space

Changes of variables (replacement with more concrete ones):

The operations

Dynamic Part - generalized substitutions refinement of substitutions.

Introduce refinement substitutions

(until reaching programming substitutions).

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Refinement

#### Approach of refinement: How to refine?

Introducing data structures and replacing abstract structures by concrete ones.

 Use the clause REFINES to link the abstract machine witj its refinement

REFINEMENT

MM R1

REFINES

MM

F.ND

- Refining the state space:
  - introduce new (concrete) variables,
  - choice of (less abstract) structures,
  - binding abstract and concrete variables bay a binding invariant

#### Approach of refinement: How to refine?

- Refinement of the operations:
  - The interface should not be modified.
  - Rewrite the abstract operations with the new variables and the appropriate substitutions (introducing sequences, loop, local variables).
  - Introduce refinement substitutions.
  - Remove non-determinism
  - Weak in the concrete refined machine, the preconditions of the abstract operations, until they disappear.
- ⇒ extending the substitution language.

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Refinement

# **Examples of refinement**

#### Aready seen:

- Resource Allocation
- Euclidian Division

#### **Example refinement**

- Modeling and development of a resource allocation system
- There are N resources to allocate/free
- The allocation is done according to the availability of the resources
- the allocated resources are free after a while

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Refinement

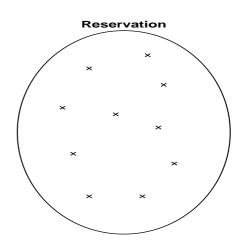
# Example: resource allocation

 $n_{rsrc} \in 0..100$ 

n\_rsrc = cardinal of the set

allocate  $\rightarrow$  - 1 element

free  $\rightarrow$  + 1 element



```
OPERATIONS
MACHINE
     Allocation
                             allocate =
                                 PRE
                                      n rsrc > 0
VARIABLES
                                 THEN
                                      n_rsrc := n_rsrc - 1
     n_rsrc
                                 END
INVARIANT
                             free =
     n_rsrc : 0..100
                                 PRE
                                      n_r < 100
INITIALISATION
                                 THEN
     n_rsrc := 100
                                      n_rsrc := n_rsrc + 1
                                 END
                             bb <-- available =
                                  bb :: BOOL
                             // ou bb := bool(0 < n_rsrc)
                              END
                                      ₹ 990
```

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Refinement

# **Consistency Proof**

The developer of the abstract machine has to kinds of PO: To prove that the INITIALISATION establishes the invariant

```
[n\_rsrc := 100](n\_rsrc \in 0..100)
```

we should prove that  $100 \in 0..100$ 

#### **Consistency Proof**

We have to prove that each operation called under its PREcondition, preserve the invariant.

• for the operation *allocate* we should prove:

```
n\_rsrc \in 0..100 \land 0 < n\_rsrc \Rightarrow n\_rsrc - 1 \in 0..100
```

• for the operation available we should prove:

```
n\_rsrc \in 0..100 \land (n\_rsrc > 0 \lor \neg (n\_rsrc > 0))

\Rightarrow

n\_rsrc \in 0..100
```

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Refinement

## Resource allocation (Refinement)

# Reservation1 x r\_occupées x r\_libres

allocate  $\rightarrow$  find 1 free element free  $\rightarrow$  find 1 unavailable element

```
REFINEMENT
  Allocation_R1
REFINES
  Allocation
VARIABLES
    rs_free, rs_unavailable // n_rscrc est incluse
// new less abstract variables
INVARIANT
    rs_free : POW(INTEGER)
& rs_unavailable : POW(INTEGER)
& rs_free /\ rs_unavailable = {}
& n_rsrc = card(rs_free) // binding invariant
INITIALISATION
    rs_free, rs_unavailable, n_rsrc := 1..100, {}, 100
```

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#### Refinement

```
free = // rewritten with the new variables
ANY ss WHERE
                                    bb <-- available =
                                        IF 0 < n_rsrc</pre>
    ss : rs_unavailable
 THEN
                                        THEN
     rs_free := rs_free \/ {ss}
                                           bb := TRUE
 || rs_unavailable :=
                                       ELSE
           rs_unavailable - {ss}
                                           bb := FALSE
 || n_rsrc := n_rsrc + 1
                                       END
END
                                    END
```

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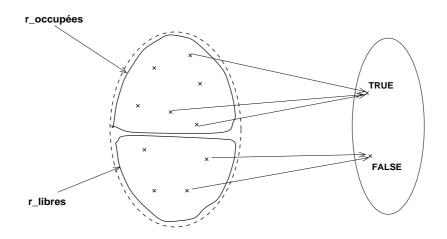
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#### Refinement

# Resource allocation (Implementation)

#### Implantation





#### Structure of the implementation

```
IMPLEMENTATION
   Allocation_I1
REFINES
   Allocation_R1
IMPORTS
   ... // import predefined machines
VARIABLES
   ... // new concrete variables
INVARIANT
   ...
INITIALISATION
   ...
OPERATIONS
   ... // They are now rewritten with refinement subst.
   and programming substitutions
```

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Refinement

#### Refinement substitutions

#### Sequential substitutions

```
Let S and T be substitutions,
the sequential substitution is noted: S; T
Its semantic definition is expressed with:
[S;T]R \equiv [S][T]R\equiv [S]([T]R)S \text{ establishes } [T]R
```

#### Refinement substitutions

#### Loop substitution

The loop substitution has the following shape:

```
while P do S invariant I variant V end
```

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Refinement

# Semantic of the loop substitution

#### Semantically, it is

```
I \land 
/* the variant is a natural */

\forall x.(I \Rightarrow V \in NATURAL) \land 
/* the variant decreases after each step */

\forall (x,n).(I \land P \Rightarrow [n := V][S](V < n)) \land 
/* continuation of the loop */

\forall x.(I \land P \Rightarrow [S]I) \mid 
@x'.([x := x'](I \land \neg P) \Rightarrow x := x'))
```

#### Substitution VAR ... IN

Block with local variables

```
The notation is:
```

```
var x in // introduction of local variables
S
end
```

4□ ▶ 4□ ▶ 4 = ▶ 4 = ▶ 9 < 0</p>

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Modularization: Construction of Large Software

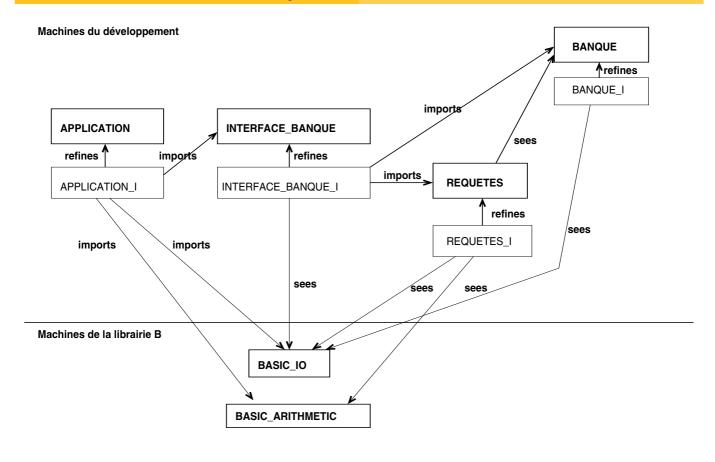
## **Architecture of Large Systems**

Composition of machines  $\rightarrow$  large machines.

- Modules Composition Layered Architecture
- Modularity

#### Composition of machines

- Hierarchy with the clauses INCLUDES, EXTENDS, PROMOTES
- Sharing with the clauses SEES, USES



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Modularization: Construction of Large Software

# Hierarchy

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INCLUDES to include a machine in another one+ promotion of some operations PROMOTES

```
MACHINE

MA
INCLUDES

MB /* access by Opmb to varB */
PROMOTES

Opmb1, Opmb3 /* become operations of MA */
...
END
```

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# Hierarchy

#### EXTENDS, inclusion but no need to promote

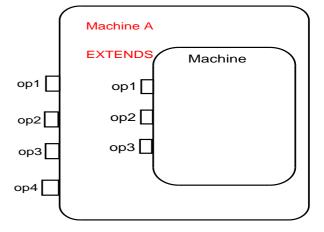
#### MACHINE

MA

**EXTENDS** 

MB

END



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Modularization: Construction of Large Software

# **Sharing**

#### SEES for a read only sharing

MACHINE

MA

**SEES** 

MB

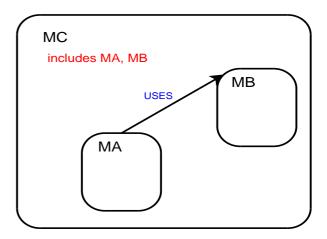
• • •

**END** 

# **Sharing**

#### USES for a read/write sharing

MACHINE
MA
USES
MB
...
END



MA et MB should be included in another machine.



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